Multispecies ASEP and t-PushTASEP on a ring and a strange five vertex model

Atsuo Kuniba (Univ. Tokyo)

Program on Classical, Quantum and Probabilistic Integrable Systems - Novel Interactions and Applications @ CMSA, Harvard, Boston

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This talk is an elementary exposition of algebraic and combinatorial aspects of Inhomogeneous t-PushTASEP and Asymmetric Simple Exclusion Process (ASEP) on 1D periodic lattice which become intriguing in multispecies setting.

Contents (key words)

Antisymmetric fusion, strange five vertex model, Holstein-Primakov realization of U_q , 3D interpretation of stationary probability, corner transfer matrix, t-oscillator algebra, multiline queue construction, etc.

Based on

A strange five vertex model and multispecies ASEP on a ring, K-Okado-Scrimshaw, arXiv:2408.12092,

Multispecies inhomogeneous t-PushTASEP from antisymmetric fusion, Ayyer-K, arXiv:2503.00829 [Corwin-Petrov13, Borodin-Wheeler22, Ayyer-Martin23, Aggarwal-Nicoletti-Petrov23,...]



1D periodic chain with L sites

$$\sigma_i \in \{0, 1, \ldots, n\}$$

0: empty site 1,...,n: species (or color) of particles

$$V = \bigoplus_{\alpha=0}^{n} \mathbb{C} | \alpha \rangle$$
 space of one particle states

The space of states of t-PushTASEP is the subspace

$$\mathbb{V}(\mathbf{m}) \subset V^{\otimes L} = \bigoplus_{0 \leq \sigma_1, \dots, \sigma_L \leq n} \mathbb{C} | \sigma_1, \dots, \sigma_L \rangle$$

specified by $\mathbf{m} = (m_0, \ldots, m_n)$, where $m_i =$ number of type *i* particles.

We assume $m_i \ge 1$ for all $0 \le i \le n$. $K_i = m_0 + \dots + m_{i-1}$ $(0 \le i \le n)$

State vector at time s

Master equation

$$|\mathbb{P}(s)\rangle = \sum_{\sigma} \mathbb{P}(\sigma; s) |\sigma\rangle$$
 $\frac{d}{ds} |\mathbb{P}(s)\rangle = H_{\text{PushTASEP}}(x_1, \dots, x_L) |\mathbb{P}(s)\rangle$

$$H_{\text{PushTASEP}}(x_1, \dots, x_L) |\boldsymbol{\sigma}\rangle = \sum_{\boldsymbol{\sigma}'} \sum_{j=1}^L \frac{1}{x_j} \prod_{\substack{1 \leq h \leq n \\ \text{moved}}} w_{\boldsymbol{\sigma}, \boldsymbol{\sigma}'}(h) |\boldsymbol{\sigma}'\rangle - \Big(\sum_{j=1}^L \frac{[\sigma_j \geq 1]}{x_j}\Big) |\boldsymbol{\sigma}\rangle$$



Example. n=2, L=4.

 $H_{\mathrm{PushTASEP}}(x_1,\ldots,x_4)|0121
angle$

$$=\frac{|1021\rangle}{x_2} + \frac{|1102\rangle}{(1+t+t^2)x_3} + \frac{t|2101\rangle}{(1+t+t^2)x_3} + \frac{t^2|1201\rangle}{(1+t+t^2)x_3} + \frac{|1120\rangle}{x_4} - \left(\frac{1}{x_2} + \frac{1}{x_3} + \frac{1}{x_4}\right)|0121\rangle$$

Th. [Ayyer-K,2025] $H_{\text{PushTASEP}}(x_1, \dots, x_L) = \frac{1}{(1-t)\prod_{i=1}^n (1-t^{K_i})} \sum_{k=0}^{n+1} (-1)^{k-1} \left. \frac{dT^k(z|x_1, \dots, x_L)}{dz} \right|_{z=0} - \left(\sum_{j=1}^L \frac{1}{x_j} \right) \text{Id}$

 $T^k(z|x_1,\ldots,x_L)$: commuting transfer matrix of $U_t(\hat{sl}_{n+1})$ vertex model $(0 \le k \le n+1)$

$$[T^{k}(z|x_{1},\ldots,x_{L}),T^{k'}(z'|x_{1},\ldots,x_{L})] = 0 \qquad (0 \le k,k' \le n+1)$$

z: spectral parameter, x_j : inhomogeneity at site j

auxiliary space = k-th fundamental (degree k antisymmetric tensor) representation $V^k (V^1 = V)$

Individual $T^k(z|x_1,...,x_L)$ and its derivative at z = 0 are *not* stochastic in general.

A kind of inclusion-exclusion principle that selects sequential particle transitions while canceling unwanted channels.

Two natural labeling sets for the base of V^k

$$\mathcal{T}^{k} = \{ \mathbf{A} = (A_{1}, \dots, A_{k}) \mid 0 \leq A_{1} < \dots < A_{k} \leq n \} : \text{ tableau representation}$$
$$\mathcal{B}^{k} = \{ \mathbf{a} = (a_{0}, \dots, a_{n}) \in \{0, 1\}^{n+1} \mid a_{0} + \dots + a_{n} = k \} : \text{ multiplicity representation}$$

$$T^{k}(z|x_{1},\ldots,x_{L})|\sigma_{1},\ldots,\sigma_{L}\rangle = \sum_{\sigma'_{1},\ldots,\sigma'_{L}} T^{k}(z|x_{1},\ldots,x_{L})^{\sigma'_{1},\ldots,\sigma'_{L}}_{\sigma_{1},\ldots,\sigma_{L}}|\sigma'_{1},\ldots,\sigma'_{L}\rangle$$

$$T^{k}(z|x_{1},\ldots,x_{L})_{\sigma_{1},\ldots,\sigma_{L}}^{\sigma'_{1},\ldots,\sigma'_{L}} = \sum_{\mathbf{a}_{1},\ldots,\mathbf{a}_{L}\in\mathcal{B}^{k}} \mathbf{a}_{1} \xrightarrow[\frac{z}{x_{1}}]{\sigma_{1}} \mathbf{a}_{2} \xrightarrow[\frac{z}{x_{2}}]{\sigma_{2}} \mathbf{a}_{3} \longrightarrow \cdots \longrightarrow \mathbf{a}_{L} \xrightarrow[\frac{z}{x_{L}}]{\sigma_{L}} \mathbf{a}_{1}$$

$$\mathbf{i} \xrightarrow{j}_{j} \mathbf{a} = \delta^{\mathbf{a} + \mathbf{e}_{b}}_{\mathbf{i} + \mathbf{e}_{j}} (-1)^{a_{0} + \dots + a_{j-1} + i_{0} + \dots + i_{b-1}} t^{a_{j+1} + \dots + a_{n}} (1 - t^{a_{j}} z^{\delta_{b,j}}) z^{[j>b]}$$

$$(\mathbf{e}_{j} = (0, \dots, \overset{j}{1}, \dots, 0) : j \text{ th elementary vector in } \mathbb{Z}^{n+1})$$

This is a special case $(k_1, k_2) = (k, 1)$ of the quantum R matrix $S^{k_1, k_2}(z) \in \text{End}(V^{k_1} \otimes V^{k_2})$. It can be constructed either from 3D *L*-operator or antisymmetric fusion of $S^{1,1}(z)$.



 $0 \leq b, j \leq n$ $\mathbf{i} = (I_1, \dots, I_k), \mathbf{a} = (A, \dots, A_k) \in \mathbb{T}^k$ are tableau representations

Example. n=2, L=4.

$$H_{\text{PushTASEP}}(x_1, \dots, x_4) |0121\rangle = \frac{|1021\rangle}{x_2} + \frac{|1102\rangle}{(1+t+t^2)x_3} + \frac{t|2101\rangle}{(1+t+t^2)x_3} + \frac{t^2|1201\rangle}{(1+t+t^2)x_3} + \frac{|1120\rangle}{x_4} - \left(\frac{1}{x_2} + \frac{1}{x_3} + \frac{1}{x_4}\right) |0121\rangle$$

$$H_{\text{PushTASEP}}(x_1, \dots, x_4) = -\frac{\dot{T}^0(0|x_1, \dots, x_4) - \dot{T}^1(0|x_1, \dots, x_4) + \dot{T}^2(0|x_1, \dots, x_4) - \dot{T}^3(0|x_1, \dots, x_4)}{(1-t)^2(1-t^3)} - \left(\frac{1}{x_1} + \frac{1}{x_2} + \frac{1}{x_3} + \frac{1}{x_4}\right) \text{Id}$$

$$\begin{split} T^{0}(z)|0121\rangle &= \mathcal{D}_{0}(z)|0121\rangle, \quad T^{3}(z)|0121\rangle = \mathcal{D}_{3}(z)|0121\rangle, \\ T^{1}(z)|0121\rangle &= \frac{(1-t)^{4}z^{2}}{x_{2}x_{3}}|1012\rangle - \frac{(1-t)^{3}z(z-x_{2})}{x_{2}x_{3}}|1102\rangle + \frac{(1-t)^{2}tz(z-x_{1})(tz-x_{2})}{x_{1}x_{2}x_{3}}|0112\rangle \\ &+ \frac{(1-t)^{2}z(z-x_{2})(z-x_{3})}{x_{2}x_{3}x_{4}}|1120\rangle + \frac{(1-t)^{2}t^{2}z(z-x_{1})(z-x_{4})}{x_{1}x_{3}x_{4}}|0211\rangle - \frac{(1-t)^{3}tz^{2}(z-x_{4})}{x_{2}x_{3}x_{4}}|2011\rangle \\ &+ \frac{(1-t)^{2}tz(z-x_{2})(z-x_{4})}{x_{2}x_{3}x_{4}}|2101\rangle + \frac{(1-t)^{2}z(z-x_{3})(tz-x_{4})}{x_{2}x_{3}x_{4}}|1021\rangle + \mathcal{D}_{1}(z)|0121\rangle, \\ T^{2}(z)|0121\rangle &= \frac{(1-t)^{2}tz(tz-x_{1})(tz-x_{2})}{x_{1}x_{2}x_{3}}|0112\rangle + \frac{(1-t)^{4}t^{2}z^{2}}{x_{3}x_{4}}|1210\rangle + \frac{(1-t)^{3}t^{2}z^{2}(tz-x_{2})}{x_{2}x_{3}x_{4}}|2110\rangle \\ &+ \frac{(1-t)^{2}t^{3}z(z-x_{2})(tz-x_{3})}{x_{2}x_{3}x_{4}}|1120\rangle + \frac{(1-t)^{2}t^{2}z(tz-x_{1})(z-x_{4})}{x_{1}x_{3}x_{4}}|0211\rangle + \frac{(1-t)^{3}t^{2}z(tz-x_{4})}{x_{3}x_{4}}|1201\rangle \\ &+ \frac{(1-t)^{2}t^{2}z(tz-x_{2})(tz-x_{4})}{x_{2}x_{3}x_{4}}|2101\rangle + \frac{(1-t)^{2}t^{3}z(tz-x_{3})(tz-x_{4})}{x_{2}x_{3}x_{4}}|1021\rangle + \mathcal{D}_{2}(z)|0121\rangle. \end{split}$$

$$\begin{split} \dot{T}^{0}(0)|0121\rangle &= \dot{\mathcal{D}}_{0}(0)|0121\rangle, \quad \dot{T}^{3}(0)|0121\rangle = \dot{\mathcal{D}}_{3}(0)|0121\rangle, \qquad (\mathcal{D}_{k}(z): \text{ coefficient of diagonal term}) \\ \dot{T}^{1}(0)|0121\rangle &= \frac{(1-t)^{2}}{x_{2}}|1021\rangle + \frac{(1-t)^{2}t}{x_{3}}|0112\rangle + \frac{(1-t)^{2}t^{2}}{x_{3}}|0211\rangle \\ &+ \frac{(1-t)^{3}}{x_{3}}|1102\rangle + \frac{(1-t)^{2}t}{x_{3}}|2101\rangle + \frac{(1-t)^{2}}{x_{4}}|1120\rangle + \dot{\mathcal{D}}_{1}(0)|0121\rangle, \\ \dot{T}^{2}(0)|0121\rangle &= \frac{(1-t)^{2}t^{3}}{x_{2}}|1021\rangle + \frac{(1-t)^{2}t^{2}}{x_{3}}|0112\rangle + \frac{(1-t)^{2}t^{2}}{x_{3}}|0211\rangle \\ &- \frac{(1-t)^{3}t^{2}}{x_{3}}|1201\rangle + \frac{(1-t)^{2}t^{2}}{x_{3}}|2101\rangle + \frac{(1-t)^{2}t^{3}}{x_{4}}|1120\rangle + \dot{\mathcal{D}}_{2}(0)|0121\rangle. \end{split}$$

Turning to n-Species ASEP

$$H_{\text{ASEP}} = \sum_{i \in \mathbb{Z}_L} \underbrace{1 \otimes \cdots \otimes 1}_{i \otimes \dots \otimes 1} \otimes h_{\text{ASEP}} \otimes \underbrace{1 \otimes \cdots \otimes 1}_{i \otimes \dots \otimes 1} \qquad \text{(Markov matrix)}$$
$$h_{\text{ASEP}}(|\alpha\rangle \otimes |\beta\rangle) = (|\beta\rangle \otimes |\alpha\rangle - |\alpha\rangle \otimes |\beta\rangle)t^{[\alpha > \beta]} \qquad \text{(local Markov matrix)}$$

Well-known origin in homogeneous T¹(z)

$$H_{\text{ASEP}} = -(1-t)\frac{d}{dz}\log T^1(z|\mathbf{x}=\mathbf{1})|_{z=1} - tL \operatorname{Id},$$
 (known as ``Baxter type formula")

where $\mathbf{x} = \mathbf{1}$ means the homogeneous specialization $x_1 = \cdots = x_L = 1$.

This is due to the following properties of the basic (non-fusioned) R-matrix at the Hamiltonian point z = 1:

$$S^{1,1}(1) = (1-t)\mathcal{P}, \quad \mathcal{P}(|\alpha\rangle \otimes |\beta\rangle) = |\beta\rangle \otimes |\alpha\rangle, \quad \mathcal{P}\left.\frac{dS^{1,1}(z)}{dz}\right|_{z=1} = -h_{\text{ASEP}} - t \,\text{Id}$$

Corollary

 $[T^1(z|\mathbf{x}=\mathbf{1}), T^k(z'|\mathbf{x}=\mathbf{1})] = 0$ leads to $[H_{\text{ASEP}}, H_{\text{PushTASEP}}(\mathbf{x}=\mathbf{1})] = 0.$

ASEP and homogeneous t-PushTASEP share the same eigenstates.

Joint eigenvector of T^k corresponding to the t-Push TASEP stationary state

$$\Lambda^{k}(z|x_{1},\ldots,x_{L}) = e_{k-1}(t^{K_{1}},\ldots,t^{K_{n}})\prod_{j=1}^{L}\left(1-\frac{tz}{x_{j}}\right) + e_{k}(t^{K_{1}},\ldots,t^{K_{n}})\prod_{j=1}^{L}\left(1-\frac{z}{x_{j}}\right)$$

 $e_k(z_1, \ldots, z_n) = \sum_{i_1, \ldots, i_n = 0, 1, i_1 + \cdots + i_n = k} z_1^{i_1} \cdots z_n^{i_n}$ (degree k elementary symmetric polynomial)

$$H_{\text{PushTASEP}}(x_1, \dots, x_L) = \frac{1}{(1-t)\prod_{i=1}^n (1-t^{K_i})} \frac{d}{dz} \sum_{k=0}^{n+1} (-1)^{k-1} \left(T^k(z|x_1, \dots, x_L) - \Lambda^k(z|x_1, \dots, x_L) \right) \Big|_{z=0}$$

We construct the stationary state of t-PushTASEP as a joint eigenstate

$$T^{k}(z|x_{1},\ldots,x_{L})|\mathbb{P}_{\mathrm{mp}}\rangle = \Lambda^{k}(z|x_{1},\ldots,x_{L})|\mathbb{P}_{\mathrm{mp}}\rangle \qquad (0 \leq k \leq n+1)$$

in a matrix product (mp) form

$$|\mathbb{P}_{\mathrm{mp}}\rangle = \sum_{\sigma_1,\ldots,\sigma_L} \operatorname{Tr} \left(A_{\sigma_1}(x_1) \cdots A_{\sigma_L}(x_L) \right) |\sigma_1,\ldots,\sigma_L\rangle \in \mathbb{V}(\mathbf{m})$$

The operators $A_0(x), \ldots, A_n(x)$ are "corner transfer matrices" of a strange five vertex model (to be explained in detail below).

They satisfy the Zamolodchikov-Faddeev(ZF) algebra with structure function $S^{1,1}(z)$.

$$\Big(1-rac{tz}{x}\Big)A_{lpha}(x)A_{eta}(z) = \sum_{\gamma,\delta=0}^{n} \qquad \begin{array}{c} lpha & \gamma & \beta \\ \gamma & z & \delta \end{array} \quad A_{\gamma}(z)A_{\delta}(x)$$

$$T^1(z|x_1,\ldots,x_L)|\mathbb{P}_{\mathrm{mp}}
angle \stackrel{?}{=} \Lambda^1(z|x_1,\ldots,x_L)|\mathbb{P}_{\mathrm{mp}}
angle \qquad ext{ is depicted as}$$



(#) is a polynomial equation in z of degree at most *L*. Suffices to check at $z = 0, x_1, \dots, x_L$. (Crucial advantage of introducing the inhomogeneity.)

z = 0 is easy. $z = x_1$ case is shown by successive application of ZF-algebra relation as



Example of stationary state in $\mathbb{V}(\mathbf{m})$ for n = 2

$$\mathbf{m} = (1, 1, 1): \quad \frac{tx_1 + x_3 + tx_3}{x_1} |012\rangle + \frac{x_2 + x_3 + tx_3}{x_2} |102\rangle + \text{cyc.}$$

$$\mathbf{m} = (1, 2, 1): \quad \frac{t^2x_1 + x_4 + tx_4 + t^2x_4}{x_1} |0112\rangle + \frac{tx_2 + x_4 + tx_4 + t^2x_4}{x_2} |1012\rangle + \frac{x_3 + x_4 + tx_4 + t^2x_4}{x_3} |1102\rangle + \text{cyc.}$$

$$\mathbf{m} = (2, 2, 1):$$

$$\frac{t^2x_1 + t^2x_2 + x_5 + tx_5 + t^2x_5}{x_1x_2} |00112\rangle + \frac{t^2x_1 + tx_3 + x_5 + tx_5 + t^2x_5}{x_1x_3} |01012\rangle + \frac{tx_2 + tx_3 + x_5 + tx_5 + t^2x_5}{x_2x_3} |10012\rangle$$

$$\frac{t^2x_1 + x_4 + x_5 + tx_5 + t^2x_5}{x_1x_2} |00112\rangle + \frac{tx_2 + x_4 + x_5 + tx_5 + t^2x_5}{x_1x_3} |01012\rangle + \frac{tx_2 + tx_3 + x_5 + tx_5 + t^2x_5}{x_2x_3} |10012\rangle$$

$$+\frac{1}{x_1x_4}|01102\rangle +\frac{1}{x_2x_4}|10102\rangle +\frac{1}{x_2x_4}|10102\rangle +\frac{1}{x_3x_4}|1002\rangle +cyc.$$

cyc. means the terms obtained by cyclic permutation $|\sigma_1, \ldots, \sigma_L \rangle \rightarrow |\sigma_L, \ldots, \sigma_{L-1} \rangle, x_i \rightarrow x_{i+1}$.

The coefficients are also called "ASEP polynomials", although ASEP stationarity is valid only in the homogeneous specialization $\forall x_i = 1$. (In that sense, they may better be called "PushTASEP polynomials".)

From now on, we change the label of local states as $0, 1, \ldots, n \rightarrow n, \ldots, 1, 0$, and set

$$X_{\alpha}(z) = A_{n-\alpha}(z^{-1}) \quad (0 \le \alpha \le n)$$

Before explaining its construction by a strange five vertex model, a brief review of relevant results is in order.

Constructions of stationary states of multispecies ASEP on a ring

Algebraic	Combinatorial
Matrix product operators	Multiline queue method
Prolhac-Evans-Mallick 2009	t=0: Ferrari-Martin (FM) 2009
Representations of ZF algebra	t=t: Martin 2020
Cantini-de Gier-Wheeler 2015	(t,q): Corteel-Mandelshtam-Williams 2022
(Application to Macdonald poly.)	(Application to Macdonald poly.)
t=0: ZF alg. from tetrahedron eq.	t=0: FM algorithm from quantum groups
K-Maruyama-Okado 2016	K-Maruyama-Okado 2015

The key in the KMO approach was a five vertex model whose Boltzmann weights are taken from t-deformed oscillator algebra at t=0.

A key for t \neq 0 ASEP and t-PushTASEP is yet another t-oscillator five vertex model which obeys a strange weight conservation rule.

It clarifies the relation of the matrix product & multiline queue methods and refines their derivations.

A strange five vertex model



2 state model; a,b,i,j = 0,1. Strange weight conservation rule a+b=j.

(cf. Usual weight conservation: $S_{ij}^{ab} = 0$ unless a + b = i + j.)

 $\mathbf{a}^+, \mathbf{a}^-, \mathbf{k}$ are generators of t-oscillator algebra:

$$k a^{\pm} = t^{\pm 1} a^{\pm} k$$
, $a^{-} a^{+} = 1 - t k$, $a^{+} a^{-} = 1 - k$.

A natural representation on a bosonic Fock space:

$$F := \bigoplus_{d=0}^{\infty} \mathbb{Q}(t) | d \rangle \qquad \mathbf{k} | d \rangle = t^d | d \rangle, \quad \mathbf{a}^+ | d \rangle = | d + 1 \rangle, \quad \mathbf{a}^- | d \rangle = (1 - t^d) | d - 1 \rangle.$$

We will also use the number operator **h** defined by $|\mathbf{h}|d\rangle = d|d\rangle$ so that $\mathbf{k} = t^{\mathbf{h}}$.

(This ket vector is not the one used for an ASEP/t-PushTASEP local state.)

Quantum picture: t-oscillator weighted 2D five vertex model

$$0 \xrightarrow{1}_{1} 0 |d\rangle = t^{d} |d\rangle \qquad 0 \xrightarrow{1}_{1} 1 |d\rangle = (1 - t^{d})|d - 1\rangle \quad \text{etc}$$

Classical picture: 3D vertex model



From now on, each 2D vertex *i* should be understood as carrying an arrow, perpendicular to it, with its own Fock space *F* running along the arrow, on which a copy of the *t*-oscillators $\mathbf{k}_i, \mathbf{a}_i^+, \mathbf{a}_i^-$ act.



Can be viewed as a **Corner Transfer Matrix(CTM)** (cf. [Baxter, Chap.13]) of the strange five vertex model.

In the classical picture, it is a layer transfer matrix of size n for a 3D vertex model defined on a triangular prism.

It is a wiring diagram for the longest element of the symmetric group S_n.

$$X_{0}(z) = \overbrace{\begin{array}{c} & 0 \\ & 0 \\ & 0 \end{array}} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array}} \begin{array}{c} & & 0 \\ & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array}} \begin{array}{c} & & & 1 \\ & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array}} \begin{array}{c} & & & 1 \\ & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array}} \begin{array}{c} & & & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array}} \begin{array}{c} & & & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 1 \end{array}} \begin{array}{c} & & & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array}} \begin{array}{c} & & & & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array}} \begin{array}{c} & & & & & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array}} \begin{array}{c} & & & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \\ & 0 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & & & & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array}} \begin{array}{c} & & & & & & & \\ & & & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array}} \begin{array}{c} & & & & & & & & \\ & & & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 0 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & & & & \\ & & & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & & \\ & & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & & \\ & & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & \\ & & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & \\ & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \begin{array}{c} & & & & \\ & & & & & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array} \xrightarrow{\begin{array}{c} & 1 \end{array}} x} \xrightarrow{\begin{array}{c} & 1 \end{array} \end{array}}\end{array}$$
}

n=3 case:



Th. [K-Okado-Scrimshaw 2024] $X_0(z), \ldots, X_n(z)$ satisfy the ZF-algebra relation.

Cor. (Unnormalized) stationary probability for t-PushTASEP on periodic lattice is given by

= Partition function of a 3D vertex model on a triangular prism whose boundary condition is specified according to $\sigma_1, \ldots, \sigma_L$.

Up to convention, $X_{\alpha}(z)$ reproduces the one in Cantini–de Gier–Wheeler [CDG 2015], where the ZF-algebra was shown by combining a couple of lemmas.

The diagram rep. for $X_{\alpha}(z)$ based on the five vertex model here is the simplest one devised to date. (Requires only 0,1 states, whereas [CDG] needs an n-color pen.)

The next page presents key ingredients of our proof, which make use of the CTM diagram and elucidate an connection to the quantum group theory.

n-reducing recursion relation = immediate consequence of the CTM diagram



The factor $\mathcal{T}(z)_{ij}$ is linked with the quantum group theory via

$$\mathcal{L}_{\alpha,\beta} = \mathcal{T}(z)_{\alpha,\beta+1} (\mathbf{a}_n^-)^{\delta_{\beta n}} (z^{-1} \mathbf{k}_n)^{\theta(\beta \neq n)} \quad (0 \leq \alpha \leq n-1, \, 0 \leq \beta \leq n),$$

$$\mathcal{L}_{\alpha,\beta} = \alpha \xrightarrow{\mathbf{k} = 0} \beta = \begin{cases} \mathbf{k}_{\beta+1} \cdots \mathbf{k}_n & (\alpha = \beta) \\ \mathbf{a}_{\alpha}^+ \mathbf{a}_{\beta}^- \mathbf{k}_{\beta+1} \cdots \mathbf{k}_n & (\alpha < \beta) \\ 0 & (\alpha > \beta) \end{cases} \quad (0 \le \alpha, \beta \le n)$$

This $\mathcal{L}_{\alpha,\beta}$ is an *R*-matrix of $U_t(\widehat{sl}_{n+1})$ for an oscillator type representation on $\mathbb{C}^{n+1} \otimes F^{\otimes n}$, which dates back to [Holstein-Primakov 1940].

Relation to multiline queue construction

(For simplicity, homogeneous (ASEP) case $x_1 = \cdots = x_L = 1$ from now on.)



MLQ construction [Martin2020, Corteel-Mandelshtam-Williams2022]

Stationary state in
$$\mathbb{V}(\mathbf{m})$$
: $|\mathbb{P}(\mathbf{m})\rangle = \sum_{Q:\mathrm{MLQ}} \pi(Q)|_{q=1}$

Pairing for a given ball table is not unique, and the ASEP state obtained as the image of π carries a coefficient, referred to as the weight.



where the weight $wt_{q,t}(Q)$ of a MLQ is defined combinatorially as

$$\frac{(1-t)^{\ell_2}}{(qt^{\ell_1-\ell_2+1};t)_{\ell_2}} \prod_{\text{pairing line}} t^{\#\{\text{skipped balls}\}} q^{\#\text{wrapping}}$$

 $(n = 2 \text{ only. For } n \text{ general, this rule is applied with } q \text{ replaced by } q^{\bullet} \text{ for some } \bullet.)$



= Generating sum of MLQ weights, where dependence on **a**, **b**, **i**, **j** is specified by



Define
$$S(q,t)_{\mathbf{i},\mathbf{j}}^{\mathbf{a},\mathbf{b}} := (1 - qt^{|\mathbf{j}| - |\mathbf{i}|}) \operatorname{Tr} \left(q^{\mathbf{h}} S_{i_1 j_1}^{a_1 b_1} \cdots S_{i_L j_L}^{a_L b_L} \right)$$
 $(\mathbf{h}|d\rangle = d|d\rangle)$

= BBQ stick with X shape sausages

$$\operatorname{Tr}_{F}\left(\begin{array}{ccc} \overset{\mathsf{gh}}{\swarrow} & \overset{\flat_{\mathfrak{l}}}{\underset{\mathfrak{j}_{\mathfrak{l}}}{\checkmark}} & \overset{\flat_{\mathfrak{l}}}{\underset{\mathfrak{j}_{\mathfrak{l}}}{\checkmark}} & \overset{\flat_{\mathfrak{l}}}{\underset{\mathfrak{j}_{\mathfrak{l}}}{\checkmark}} \\ & \overset{\flat_{\mathfrak{l}}}{\underset{\mathfrak{j}_{\mathfrak{l}}}{\checkmark}} & \overset{\flat_{\mathfrak{l}}}{\underset{\mathfrak{j}_{\mathfrak{l}}}{\checkmark}} \end{array}\right)$$

This is also vanishing unless **a** + **b** = **j** reflecting the strange five vertex model.

Th. [K-Okado-Scrimshaw2024] $M(q,t)^{\mathbf{a},\mathbf{b}}_{\mathbf{i},\mathbf{j}}=S(q,t)^{\mathbf{a},\mathbf{b}}_{\mathbf{i},\mathbf{j}}$

Example in the previous page:

$$M(q,t)_{\mathbf{i},\mathbf{j}}^{\mathbf{a},\mathbf{b}} = \frac{(1-t)qt^2}{1-qt^4} \frac{(1-t)t}{1-qt^3} + \frac{1-t}{1-qt^4} \frac{1-t}{1-qt^3} = \frac{(1-t)^2(1+qt^3)}{(1-qt^4)(1-qt^3)},$$

$$\begin{split} S(q,t)_{\mathbf{i},\mathbf{j}}^{\mathbf{a},\mathbf{b}} &= (1-qt^2) \operatorname{Tr}(q^{\mathbf{h}} S_{00}^{00} S_{01}^{10} S_{10}^{00} S_{01}^{01} S_{10}^{00} S_{00}^{00} S_{01}^{01}) \\ &= (1-qt^2) \operatorname{Tr}(q^{\mathbf{h}} \mathbf{a}^{-} \mathbf{a}^{+} \mathbf{k} \, \mathbf{a}^{-} \mathbf{a}^{+} \mathbf{k}) \\ &= (1-qt^2) \sum_{d \ge 0} q^d (1-t^{d+1}) t^d (1-t^{d+1}) t^d = \frac{(1-t)^2 (1+qt^3)}{(1-qt^4)(1-qt^3)}. \end{split}$$

A messy sum over the pairings is unified into a single BBQ stick (=Trace) of 5V. What is 'created' or 'annihilated' by t-oscillator algebra are the customers in the queue. What about $n \ge 3$?

n=3 example



The MLQ construction for $n \ge 3$ is a nested composition of the n=2 rule in a "CTM manner" as illustrated in the next page.



The vertices in the last CTM diagram represent $M(q, t)_{i,i}^{a,b}$.

Making the substitution $M(q,t)_{i,j}^{\mathbf{a},\mathbf{b}} = S(q,t)_{i,j}^{\mathbf{a},\mathbf{b}}$ (BBQ stick)



Vertex encoding MLQ weights

BBQ stick made of the strange five vertex model

and setting q = 1, one reproduces the matrix product formula for stationary probabilities, where each layer is a CTM of the strange 5 vertex model (n = 3 example shown).





Generating sum of MLQ weights

Problems/Questions/Remarks

Superposition over the fundamental representations implies

dim(effective auxiliary space) =
$$\binom{n+1}{0} + \binom{n+1}{1} + \dots + \binom{n+1}{n+1} = 2^{n+1}$$

Does this suggest a simpler reformulation of t-PushTASEP?

Are there further examples of commuting transfer matrices that are not stochastic individually, but become so through some form of superposition? What about type BCD ?

A direct proof of the ZF algebra via a tetrahedron equation (3D analogue of the Yang– Baxter eq.), without relying on induction on n, remains to be found. (It is known for t=0 [KMO16]).

A further remark

It is also possible to express $H_{\text{PushTASEP}}(x_1, \ldots, x_L)$ in terms of $T_k(z) = T_k(z|x_1, \ldots, x_L)$, which is the commuting transfer matrix whose auxiliary space is the degree k symmetric tensor representation.

$$[T_k(z|x_1, \dots, x_L), T_{k'}(z'|x_1, \dots, x_L)] = 0 \qquad (k, k' \in \mathbb{Z}_{\ge 0}),$$

$$[T_k(z|x_1, \dots, x_L), T^l(z'|x_1, \dots, x_L)] = 0 \qquad (k \in \mathbb{Z}_{\ge 0}, l \in \{0, \dots, n+1\})$$

However, the resulting formula is not particularly illuminating. For example for n = 2, one has

$$H_{\text{PushTASEP}}(x_1, \dots, x_L) = \frac{\dot{T}_2(0) - (1 + t^{m_0} + t^{1+m_0} + t^{m_0+m_1} + t^{1+m_0+m_1})\dot{T}_1(0) + tC\sum_{j=1}^L \frac{1}{x_j}}{(1 - t)t(1 - t^{m_0})(1 - t^{m_0+m_1})},$$

 $C = -1 + t - t^{-1+m_0} - t^{2m_0} - t^{1+m_0} - t^{-1+m_0+m_1} - t^{2(m_0+m_1)} - t^{1+m_0+m_1} - t^{-1+2m_0+m_1} - 2t^{2m_0+m_1} - 2t^{2m_0+m_1} - t^{-1+2m_0+m_1} - t^{2m_0+m_1} - t^$

where $\dot{T}_l(0) = \left. \frac{dT_l(z)}{dz} \right|_{z=0}$